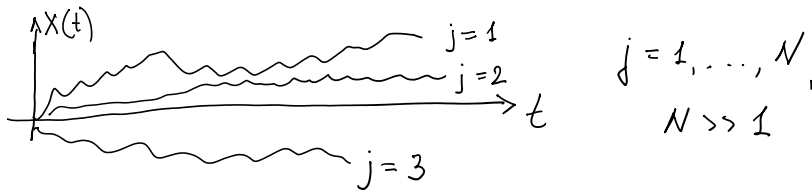


Reminder 1. Stochastic Processes

$X = f(t)$ random function of time



$Y = f(\vec{r})$ random function of coordinates

" Random field (random surface $Z = f(x, y)$)

Stoch Proc fully characterized by n -point PDFs

- $p_n(x_1, t_1; x_2, t_2; \dots, x_n, t_n) \quad \forall n$

- n -point moments, e.g.

$$\langle x(t_1) x(t_2) \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 x_2 p_2(x_1, t_1; x_2, t_2) dx_1 dx_2$$

- n -point characteristic functions

$$\hat{p}_n(k_1, t_1; k_2, t_2; \dots; k_n, t_n) = \int \dots \int e^{ik_1 x_1 + ik_2 x_2 + \dots + ik_n x_n} p_n(x_1, t_1; \dots; x_n, t_n) dx_1 \dots dx_n$$

Fortunately, for most practical purposes enough to know $n=1, 2$.

Reminder 2 Important classes of stoch Proc.

Stationary processes

strictly stationary

$$p_n(x_1, t+\tau; \dots; x_n, t+\tau) = p_n(x_1, t_1; \dots; x_n, t_n)$$

wide sense stationary

$$\langle x(t) \rangle = \text{const}$$

$$\langle x(t_1) x(t_2) \rangle = K(t_1 - t_2)$$

Ergodic Processes

all ensemble averages =

= corresponding time averages at $T \rightarrow \infty$

weakly ergodic (ergodicity in wide sense)

$$\langle x(t) \rangle = \overline{x^{(j)}(t)} = \frac{1}{T} \int_0^T x(t) dt$$

$$\langle x(t) x(t+\tau) \rangle = \overline{x^{(j)}(t) x^{(j)}(t+\tau)} =$$

$$\begin{aligned}\langle x(t)x(t+\tau) \rangle &= x^{(j)}(t)x^{(j)}(t+\tau) := \\ &= \frac{1}{T-\tau} \int_0^{T-\tau} x^{(j)}(t)x^{(j)}(t+\tau) dt, \\ &\quad T \rightarrow \infty\end{aligned}$$

Theorem. Only stationary processes are ergodic

Fact. "Most" of stationary processes are ergodic

Great advantage: enough to have only a single realization (trajectory)

All other processes $\Rightarrow$ Non-stationary processes
Non-stat with independent increments

Sequence $t_1 < t_2 < \dots < t_n$

$x(t_1), x(t_2) - x(t_1), x(t_3) - x(t_2), \dots, x(t_n) - x(t_{n-1})$

statistically independent

Fully characterized by

$$p(x, t) \div \hat{p}(k, t) = \langle e^{ikx(t)} \rangle$$

$$p(x_2 - x_1; t_1, t_2) \div \langle e^{ik(x(t_2) - x(t_1))} \rangle$$

Imp. Example. Gaussian process with ind. increm.

$$p(x, t) = \frac{1}{\sqrt{2\pi\sigma^2(t)}} \exp\left[-\frac{(x - \mu(t))^2}{2\sigma^2(t)}\right]$$

$$\begin{aligned}p(x_2 - x_1; t_1, t_2) &= \frac{1}{\sqrt{2\pi(\sigma^2(t_2) - \sigma^2(t_1))}} \times \\ &\times \exp\left[-\frac{(x_2 - x_1 - \mu(t_2) + \mu(t_1))^2}{2(\sigma^2(t_2) - \sigma^2(t_1))}\right]\end{aligned}$$

where $\mu(t) = \langle x(t) \rangle$

$$\sigma^2(t) = \text{Var}[x(t)] \equiv \langle x^2(t) \rangle - \langle x(t) \rangle^2$$

Markov processes (next term)

Markov processes (next term)

Non-stat. with stationary increments

- $x(t+\tau) - x(t)$ stationary in t
stat. properties of $x(t_2) - x(t_1)$ depends on $t_2 - t_1$,
but not on t_2 or t_1 separately
- structure function $S(\tau) = \langle (x(t+\tau) - x(t))^2 \rangle$
Important example $S(\tau) = \text{const.} \cdot \tau^{2H}$, $0 < H \leq 1$
Fractional Brownian motion

Non-stat. with stationary & independent increments

(Lévy processes)

$$\hat{p}(k, t) = e^{t\Psi(k)}$$

Lévy-Khinchine formula establishes explicit form of $\Psi(k)$.

Example. Wiener process $\Psi(k) = -\frac{1}{2}\sigma^2 k^2$

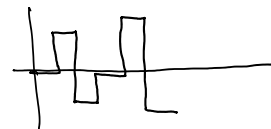
Ordinary BM with linear drift

$$\Psi(k) = ik\mu - \frac{1}{2}\sigma^2 k^2$$

- random process with independent jumps
(continuous analogue of sum of iid r.v.)

$$x(t_n) = x(t_1) + \sum_{j=2}^n [x(t_j) - x(t_{j-1})]$$

$$\text{jumps } \xi_j = x(t_j + 0) - x(t_j - 0)$$



$$x(t) = \sum_{t_j < t} \xi_j, \quad \Delta t = t_{j+1} - t_j$$

Look at previous lecture

$$\langle \xi \rangle = 0, \quad \langle \xi^2 \rangle = \sigma^2 < \infty$$

Due to CLT $\Rightarrow x(t)$ is Wiener process

Due to CLT $\Rightarrow x(t)$ is Wiener process

$$p(x,t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{x^2}{4Dt}\right)$$

Mean squared displacement $\langle x^2 \rangle = 2Dt$, $D = \frac{\sigma^2}{2\Delta t}$

• White Gaussian noise

$$\text{formally } \frac{dW}{dt} = \xi(t) = \sqrt{2D} \eta(t)$$

$$\langle \xi(t) \rangle = 0, \quad \langle \xi(t) \xi(t') \rangle = 2D \delta(t-t')$$

$$\langle \eta(t) \rangle = 0, \quad \langle \eta(t) \eta(t') \rangle = \delta(t-t')$$

End of reminder

(5.5) α -stable Lévy processes

a) Reminder. Symmetric α -stable laws

• $X, X_1, X_2, \dots, X_n$ iid strictly stable

$$\sum_{j=1}^n X_j \stackrel{d}{=} n^{1/\alpha} X, \quad 0 < \alpha \leq 2$$

• PDF $\hat{p}_X(k) = e^{-\sigma^\alpha |k|^\alpha}$

Particular cases: $\alpha=2$ $p_X(x) = \frac{e^{-x^2/4\sigma^2}}{\sqrt{4\pi\sigma^2}}$

Cauchy $\alpha=1$ $p_X(x) = \frac{\sigma}{\pi(x^2 + \sigma^2)}$

Notation $p_\alpha(x) \div \hat{p}_\alpha(k)$

• asymptotics $p_\alpha(x) \sim \frac{C(\alpha)\sigma^\alpha}{|x|^{1+\alpha}}, \quad C(\alpha) = \frac{1}{\pi} \sin\left(\frac{\pi\alpha}{2}\right) \Gamma(1+\alpha)$

$$\langle x^2 \rangle = \int_{-\infty}^{\infty} x^2 p_\alpha(x) dx = \infty$$

- GCLT $X_1, \dots, X_n$ iid non-stable, $p(x) \sim \frac{A_\alpha}{|x|^{1+\alpha}}$
 $0 < \alpha < 2, A_\alpha \text{ const}$

Properly normalized sum

$$Y_n = \frac{1}{n^{1/\alpha}} \sum_{j=1}^n X_j \Rightarrow p_{Y_n}(y) \xrightarrow{n \rightarrow \infty} p_\alpha(y) \sim \frac{A_\alpha}{|y|^{1+\alpha}}$$

$$p_\alpha(y) \div \hat{p}_\alpha(k) = e^{-\sigma_Y^\alpha |k|^\alpha} \Rightarrow$$

$$\Rightarrow \sigma_Y = \left[\frac{A_\alpha}{\sin(\frac{\pi\alpha}{2}) \Gamma(1+\alpha)} \right]^{1/\alpha}$$

End of reminder

b) random walk approximation to α -stable processes

Random walk: succession of random steps (jumps)

$$\rightarrow \text{setup } t_1=0, t_n=t, \Delta t = \frac{t}{n}, x(t) = \sum_{j=1}^n \xi_j$$

$$\xi_j \text{ } \alpha\text{-stable iid } \hat{p}_\alpha(k) = \langle e^{ik\xi_j} \rangle = e^{-\sigma^\alpha |k|^\alpha}$$

$$p(x,t) \div \hat{p}(k,t) = \langle e^{ikx(t)} \rangle = \langle e^{ik \sum_{j=1}^n \xi_j} \rangle =$$

$$= \prod_{j=1}^n \langle e^{ik\xi_j} \rangle = e^{-\sigma^\alpha |k|^\alpha n} = e^{-\sigma^\alpha |k|^\alpha \frac{t}{\Delta t}} =$$

$$= e^{-D_\alpha |k|^\alpha t}, \quad D_\alpha = \frac{\sigma^\alpha}{\Delta t}$$

PDF of α -stable process (symmetric)

$$\boxed{p_\alpha(x,t) \div \hat{p}_\alpha(k,t) = e^{-D_\alpha |k|^\alpha t}}, \quad 0 < \alpha \leq 2$$

Particular examples.

1) Wiener process $\alpha=2$ $p_{\alpha=2}(x,t) = \frac{e^{-\frac{x^2}{4Dt}}}{\sqrt{4\pi Dt}}, D \equiv D_2$

2) Cauchy process $p_{\alpha=1}(x,t) = \dots$

c) α -stable process as a random walk via GCLT
 $\rightarrow t_1 = 0, t_n = t, \Delta t = \frac{t}{n}, x(t) = \sum_{j=1}^n \xi_j$

ξ_j not α -stable iid, but $p_\xi(x)$ belongs to the domain of attraction of (symmetric)

α -stable law, $p_\xi(x) \sim \frac{A_\alpha}{|x|^{1+\alpha}}$

$$\Rightarrow \text{GCLT} \quad Z = \frac{1}{n^{1/\alpha}} \sum_{j=1}^n \xi_j$$

$$p_Z(z) \xrightarrow{n \rightarrow \infty} p_\alpha(x) \sim \frac{A_\alpha}{|x|^{1+\alpha}}, \quad \hat{p}_\alpha(k) = e^{-\sigma_z^\alpha |k|^\alpha}$$

$$\Rightarrow x(t): p(x,t) \div \hat{p}(k,t) = \langle e^{ikx(t)} \rangle =$$

$$= \langle e^{ik \sum_{j=1}^n \xi_j} \rangle = \langle e^{ik n^{1/\alpha} Z} \rangle \xrightarrow{n \rightarrow \infty} e^{-\sigma_z^\alpha |k|^\alpha n} =$$

$$= e^{-D_\alpha |k|^\alpha t}$$

$$D_\alpha = \frac{\sigma_z^\alpha}{\Delta t} = \frac{1}{\Delta t} \left[\frac{\Gamma A_\alpha}{\sin(\frac{\pi\alpha}{2}) \Gamma(1+\alpha)} \right]^{1/\alpha}$$

Conclusion, Iid random jumps (steps) belong to domain of attraction of α -stable law $\Rightarrow$

$\Rightarrow$ after many steps the resulting random walk can be viewed as α -stable Lévy process

d) Important summary

Random walks with "short" and "long" jumps

• short jumps: $\langle \xi^2 \rangle$ finite $\Rightarrow$ random walk $\rightarrow$
 $\rightarrow$ Wiener process (CLT)
 $n \rightarrow \infty$

$\xrightarrow[n \rightarrow \infty]{\sim}$ Wiener process (CLT)

- long jumps: $\langle \xi^2 \rangle$ infinite $\Rightarrow$
random walk $\xrightarrow[n \rightarrow \infty]{} \alpha$ -stable process (GCLT)

Lévy flights $\equiv$ random walk with long jumps

e) self-similarity of LFs (see self-sim. Wiener)

$$\mathcal{L}_\alpha(\lambda t) \stackrel{d}{=} \lambda^H \mathcal{L}_\alpha(t) \quad H \text{ Hurst index } (*)$$

$$\text{Use } \langle e^{ik\mathcal{L}_\alpha(t)} \rangle = e^{-D_\alpha |k|^\alpha t}$$

$$\left. \begin{array}{l} \text{lhs } (*) \quad \langle e^{ik\mathcal{L}_\alpha(\lambda t)} \rangle = e^{-D_\alpha |k|^\alpha \lambda t} \\ \text{rhs } (*) \quad \langle e^{ik\lambda^H \mathcal{L}_\alpha(t)} \rangle = e^{-D_\alpha |k|^\alpha \lambda^{H\alpha} t} \end{array} \right\} \boxed{H = \frac{1}{\alpha}}$$

$$\alpha = 2 \text{ Wiener } H = 1/2$$

f) Asymptotics, scaling variable, moments of LFs

• Asymptotics

$$\rightarrow \alpha\text{-stable rv } X \quad p_X(x) \equiv p_\alpha(x) \div \hat{p}_\alpha(k) = e^{-\sigma^\alpha |k|^\alpha}$$

$$p_\alpha(x) \underset{x \rightarrow \infty}{\sim} \frac{C(\alpha) \sigma^\alpha}{|x|^{1+\alpha}}, \quad C(\alpha) = \frac{1}{\pi} \sin\left(\frac{\pi\alpha}{2}\right) \Gamma(1+\alpha)$$

$\rightarrow \alpha$ -stable symmetric random process $\mathcal{L}_\alpha(t)$

$$p_\alpha(x, t) \div \hat{p}_\alpha(k, t) = e^{-D_\alpha |k|^\alpha t}$$

$$p_\alpha(x, t) \sim C(\alpha) \frac{D_\alpha t}{|x|^{1+\alpha}}, \quad 0 < \alpha < 2$$

• Scaling variable

$$\begin{aligned}
 p_\alpha(x, t) &= \int_{-\infty}^{\infty} e^{-ikx} \hat{p}_\alpha(k, t) \frac{dk}{2\pi} = \int_{-\infty}^{\infty} e^{-ikx - D_\alpha |k|^\alpha t} \frac{dk}{2\pi} = \\
 &= \left\{ k' = (Dt)^{1/\alpha} k \right\} = \frac{1}{(Dt)^{1/\alpha}} \int_{-\infty}^{\infty} e^{-ik'x' - |k'|^\alpha} \frac{dk'}{2\pi} = \\
 &= \left\{ x' = \frac{x}{(Dt)^{1/\alpha}} \right\} = \frac{1}{(Dt)^{1/\alpha}} p_\alpha(x') \Big|_{\sigma=1}
 \end{aligned}$$

$$\boxed{
 \begin{aligned}
 p_\alpha(x, t) &= \frac{1}{(D_\alpha t)^{1/\alpha}} p_\alpha\left(\frac{x}{(D_\alpha t)^{1/\alpha}}\right), \\
 \hat{p}_\alpha(k) &= e^{-|k|^\alpha}, \quad 0 < \alpha \leq 2
 \end{aligned}
 }$$

Example. Wiener process $p_\alpha(x, t) \rightarrow p_{\alpha=2}(x, t) =$

$$= \frac{1}{(Dt)^{1/2}} g\left(\frac{x}{(Dt)^{1/2}}\right), \quad \hat{g}(k) = e^{-k^2}$$

$$g(x) = \int_{-\infty}^{\infty} e^{-ikx - k^2} \frac{dk}{2\pi} = \frac{e^{-x^2/4}}{\sqrt{4\pi}} \Rightarrow$$

$$\Rightarrow p_{\alpha=2}(x, t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{x^2}{4Dt}\right)$$

• q-th moments

$$\langle x^2(t) \rangle = \int_{-\infty}^{\infty} x^2 p_\alpha(x, t) dx = \infty$$

$$\langle |x(t)|^q \rangle = 2 \int_0^{\infty} x^q p_\alpha(x, t) dx = 2 \int_0^{\infty} x^q \frac{1}{(Dt)^{1/\alpha}} p_\alpha\left(\frac{x}{(Dt)^{1/\alpha}}\right) dx =$$

$$= \left\{ y = \frac{x}{(Dt)^{1/\alpha}} \right\} = 2(Dt)^{q/\alpha} \int_0^{\infty} y^q p_\alpha(y) dy, \quad \hat{p}_\alpha(k) = e^{-|k|^\alpha}$$

$$p_\alpha(y) \sim \frac{1}{y^{1+\alpha}} \Rightarrow \int_0^{\infty} y^q p_\alpha(y) dy = C(q, \alpha) < \infty \quad \text{if } q < \alpha$$

$$p_\alpha(y) \sim \frac{1}{y^{1+\alpha}} \Rightarrow \int_0^y y^\eta p_\alpha(y) dy = \mathcal{L}(q, \alpha) < \infty \quad \text{if } q < \alpha$$

$$\langle |x(t)|^q \rangle \sim \begin{cases} t^{q/2} & , q < \alpha \\ \infty & , q \geq \alpha \end{cases} \quad , 0 < \alpha < 2$$

Important summary

$$\begin{array}{ll} \alpha = 2 & \text{Gauss} \\ 0 < \alpha < 2 & \end{array} \quad \langle |x|^q \rangle \sim t^{qH} \quad \left. \begin{array}{l} H = 1/2 \quad \forall q \\ H = 1/\alpha, \quad 0 < q < \alpha \end{array} \right\}$$

Remark. This is direct consequence of self-similarity

$$x(\lambda t) \stackrel{d}{=} \lambda^H x(t) \quad , \quad \lambda \rightarrow t, \quad t=1$$

$$\langle |x(t)|^q \rangle \sim \langle |t^H x(1)|^q \rangle \sim t^{qH} \langle |x(1)|^q \rangle$$

Terminology. $\langle |x(t)|^q \rangle \sim t^{f(q)}$

$f(q) = \text{const} \cdot q$ self-similar or monofractal random process

$f(q)$ nonlinear random multifractal
but $f(q)$ not arbitrary!

g) white Lévy noise (α -stable)

$$\frac{dL_\alpha(t)}{dt} = \xi_\alpha(t) \quad , \quad L_\alpha(t) = \int_0^t \xi_\alpha(t') dt'$$

$$L_\alpha(t + \Delta t) - L_\alpha(t) = L(\Delta t) - L_\alpha(0) = (\Delta t)^{1/\alpha} L_\alpha(1) \quad (**)$$

$$L_\alpha(t) : \hat{p}_\alpha(k, t) = e^{-D_\alpha |k|^\alpha t}$$

$$\text{Denote } L_\alpha(1) \equiv \xi_\alpha : \hat{p}_{\xi_\alpha}(k) = e^{-D_\alpha |k|^\alpha}$$

$$\text{Let } \xi_\alpha = D_\alpha^{1/\alpha} \eta_\alpha \Rightarrow \hat{p}_{\eta_\alpha}(k) = e^{-|k|^\alpha} \quad \uparrow \text{ standard symmetric } \alpha\text{-stable distribution}$$

Back to (* *)

$$L_\alpha(t+\Delta t) - L_\alpha(t) = (D\Delta t)^{1/\alpha} \eta_\alpha, \quad 0 < \alpha \leq 2$$

η_α standard S&S variable $\hat{p}_\alpha(k) = e^{-|k|^\alpha}$

Remark. Standard S&S with $\alpha = 2$ is $N(0, 2)$

Remember before $\eta \sim N(0, 1)$, $\langle \eta \rangle = 0$, $\langle \eta^2 \rangle = 1$

but $\langle \eta_\alpha^2 \rangle|_{\alpha=2} = 2$!

b) fractional diffusion equation

• Wiener process $\alpha = 2$ $\hat{p}_2(k, t) = e^{-Dk^2 t}$

$$\left. \begin{aligned} \frac{\partial \hat{p}_2(k, t)}{\partial t} &= -Dk^2 \hat{p}_2(k, t) \\ \hat{p}_2(k, t=0) &= 1 \end{aligned} \right\} \Rightarrow \text{eq. for } p_2(x, t)$$

$$\int_{-\infty}^{\infty} e^{-ikx} \frac{\partial \hat{p}_2(k, t)}{\partial t} \frac{dk}{2\pi} = -D \int_{-\infty}^{\infty} e^{-ikx} k^2 \hat{p}_2(k, t) \frac{dk}{2\pi}$$

$$\left. \begin{aligned} \frac{\partial p_2(x, t)}{\partial t} &= D \frac{\partial^2}{\partial x^2} p_2(x, t) \\ p_2(x, t=0) &= \delta(x) \end{aligned} \right\} \quad -\infty < x < \infty$$

$$\text{Solution } p_2(x, t) = \frac{1}{\sqrt{4\pi Dt}} e^{-x^2/4Dt}$$

• α -stable, $0 < \alpha < 2$, $\hat{p}_\alpha(k, t) = e^{-D_\alpha |k|^\alpha t}$

$$\left. \begin{aligned} \frac{\partial \hat{p}_\alpha(k, t)}{\partial t} &= -D_\alpha |k|^\alpha \hat{p}_\alpha(k, t) \\ \hat{p}_\alpha(k, t=0) &= 1 \end{aligned} \right\} \Rightarrow \text{Eq for } p_\alpha(x, t) ?$$

Digression Space fractional derivative via its Fourier transform

$$\text{FT pair} \quad \phi(x) \div \phi(k) = \int_{-\infty}^{\infty} e^{ikx} \phi(x) dx$$

$$\phi(x) = \int_{-\infty}^{\infty} e^{-ikx} \hat{\phi}(k) \frac{dk}{2\pi}$$

$$1^{\text{st}} \text{ derivative } \frac{d\phi}{dx} \div -ik \hat{\phi}(k)$$

$$2^{\text{nd}} \text{ derivative } \frac{d^2\phi}{dx^2} \div -k^2 \hat{\phi}(k)$$

$$\text{Symmetric Riesz derivative } \frac{d^\alpha \hat{\phi}}{d|x|^\alpha} \div -|k|^\alpha \hat{\phi}(k)$$

this is just the notation!

$$\alpha = 2 \quad \frac{d^2\phi}{d|x|^2} = \int_{-\infty}^{\infty} (-k^2) \hat{\phi}(k) e^{-ikx} \frac{dk}{2\pi} = \frac{d^2\phi}{dx^2}$$

$$\text{But } \frac{d\phi}{d|x|} \div -|k| \hat{\phi}(k) \Rightarrow \frac{d\phi}{d|x|} \neq \frac{d\phi}{dx}$$

$$\text{Example. } \phi(x) = \frac{1}{1+x^2} \Rightarrow \frac{d^\alpha \phi}{d|x|^\alpha} = - \int_{-\infty}^{\infty} \frac{dk}{2\pi} e^{-ikx} |k|^\alpha \hat{\phi}(k) =$$

$$= \frac{\Gamma(\alpha+1)}{\pi (1+x^2)^{(\alpha+1)/2}} \cos[(\alpha+1) \arctan x]$$

End of digression (more details next term)

$$\left| \begin{array}{l} \frac{\partial}{\partial t} p_\alpha(x, t) = D_\alpha \frac{\partial^\alpha}{\partial |x|^\alpha} p_\alpha(x, t) \\ p_\alpha(x, t=0) = \delta(x), \quad -\infty < x < \infty \end{array} \right|$$

Generalization to $d \geq 1$ via fractional Laplacian

Generalization to $d \geq 1$ via fractional Laplacian

"Normal" $\frac{\partial p}{\partial t} = D \Delta p(\vec{r}, t)$

Space-Fractional $\frac{\partial}{\partial t} p(\vec{r}, t) = -D (-\Delta)^{\alpha/2} p(\vec{r}, t)$

Assignment 3

#2 ACF $B(\tau)$ $\tau_{\text{cor}} = \frac{1}{B(0)} \int_0^\infty B(\tau) d\tau$
 $\Delta\omega = \frac{1}{G_{\text{max}}} \int_0^\infty G(\omega) d\omega$ } $\Delta\omega \cdot \tau_{\text{cor}} =$

Alternatively, $\tau_{\text{cor}} = \frac{2}{B(0)} \int_0^\infty B(\tau) d\tau$
 $\Delta\omega = \frac{2}{G_{\text{max}}} \int_0^\infty G(\omega) d\omega$

In the lecture $\tau_{\text{cor}} = \frac{2}{B(0)} \int_0^\infty B(\tau) d\tau$
 $\Delta\omega = \frac{1}{G_{\text{max}}} \int_0^\infty G(\omega) d\omega$ } $\Delta\omega \cdot \tau_{\text{cor}} = \mathcal{T}$

#3 OK

#4 OK $B_\xi(\tau) = \langle \xi(t) \xi(t+\tau) \rangle =$
 $\equiv \iiint a \cos(\eta t + \varphi) a \cos[\eta(t+\tau) + \varphi] p_\varphi p_\eta p_a d\varphi d\eta da =$
 $= \frac{\langle a^2 \rangle}{2\pi} \iint \cos(\eta t + \varphi) \cos(\eta t + \eta\tau + \varphi) p_\eta d\varphi d\eta =$
 $= \frac{\langle a^2 \rangle}{2} \int \cos(\eta\tau) p_\eta d\eta = \frac{\langle a^2 \rangle}{2} \int \frac{e^{i\eta\tau} + e^{-i\eta\tau}}{2} p_\eta d\eta =$

$$= \underbrace{\frac{\langle a^2 \rangle}{4} (\hat{p}_\eta(\tau) + \hat{p}_\eta(-\tau))}_{\neq \frac{\langle a^2 \rangle}{2} p_\eta(\tau)} \neq \frac{\langle a^2 \rangle}{2} p_\eta(\tau) !$$

#5. OK. $\xi(t) = a \cos(\omega t + \phi)$, $p(\phi) = \frac{1}{2\pi}$, $0 \leq \phi < 2\pi$

$$\begin{aligned} \hat{p}_\xi(k, t) &= \langle e^{i k a \cos(\omega t + \phi)} \rangle = \\ &= \int_0^{2\pi} \frac{d\phi}{2\pi} e^{i k a \cos \psi}, \quad \psi(t) = \omega t + \phi \quad (1) \end{aligned}$$

$$f(\psi) \equiv e^{i z \cos \psi} = \sum_{n=-\infty}^{\infty} A_n(z) e^{i n \psi} \quad (2)$$

$$A_n(z) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\psi) e^{-i n \psi} d\psi$$

Plug (2) into (1) $\Rightarrow \hat{p}_\xi(k, t) = J_0(ka)$

$$p_\xi(x) = \begin{cases} \frac{1}{\pi \sqrt{a^2 - x^2}} & , 0 \leq x < a \\ 0 & , x \geq a \end{cases}$$



#6. $\xi(t) = a \cos(\omega t + \phi)$, $p_a(x)$, $p(\phi) = \frac{1}{2\pi}$, $0 \leq \phi < 2\pi$

$$\begin{aligned} \hat{p}_\xi(k, t) &= \langle e^{i k a \cos(\omega t + \phi)} \rangle = \\ &= \int_{-\infty}^{\infty} dx p_a(x) \underbrace{\int_0^{2\pi} \frac{d\phi}{2\pi} e^{i k x \cos(\omega t + \phi)}}_{J_0(kx)} \Rightarrow \end{aligned}$$

$$\Rightarrow \hat{p}_\xi(k) = \int_{-\infty}^{\infty} J_0(kx) p_a(x) dx$$

Hankel
transformation

$$F_\nu(k) = \int_0^\infty J_\nu(kx) f(x) x dx$$

$$f(x) = \int_0^\infty F_\nu(k) J_\nu(kx) k dk$$

Used in 2D BM

Go back to #1. Cauchy is OK.

Hint. Consider Laplace. $p(x) = \frac{1}{2b} e^{-|x|/b}$ $\div$

$$\hat{p}(k) = \frac{1}{1+b^2 k^2}$$

Inf div. $\hat{p}(k) = [\hat{\phi}_n(k)]^n$ for any n

$$\begin{aligned} \frac{1}{1+b^2 k^2} &= \left[\left(\frac{1}{1-ibk} \right)^{1/n} \left(\frac{1}{1+ibk} \right)^{1/n} \right]^n = \\ &= [\hat{\phi}_n(k)]^n \end{aligned}$$

$\hat{\phi}_n(k)$ is the CF of $Y_{1n} - Y_{2n}$,

two ind identically distributed iid r.v. with CF = $\frac{1}{(1-ibk)^{1/n}}$

PDF ? $\rightarrow$

Note $p_X(x) \div \hat{p}_X(k)$

$p_Y(x) \div \hat{p}_Y(k)$

$$Y = -X \Rightarrow \hat{p}_Y(k) = \hat{p}_X^*(k)$$

End of the hint.